Derivation of the Lieb-Robinson bound

I. DEFINITION AND NOTATION

A. Definition of the system

We consider a finite-volume lattice system with spins (or sites) labeled as i = 1, 2, ..., n, where the Hilbert space of each spin is *d*-dimensional. We denote the finite set of sites as X, Y, Z and so on, and the cardinality of X as |X|(e.g. $X = \{i_1, i_2, ..., i_{|X|}\}$). We define the distance $d_{X,Y}$ as the shortest path length for which one needs to connect X to Y.

B. Definition of k-local operator

We first define the k-local operator $O^{(k)}$ as follows:

$$O^{(k)} = \sum_{|Z| \le k} o_Z,\tag{1}$$

where o_X is a local operator supported on the finite set Z. The k-local operator includes the interactions of up to k-body coupling with finite k. Explicitly, this operator can be described as

$$O^{(k)} = \sum_{i_1 < i_2 < \dots < i_k} \sum_{\mu_1, \dots, \mu_k} o^{\mu_1, \dots, \mu_k}_{i_1, \dots, i_k} s^{\mu_1}_{i_1} \otimes \dots \otimes s^{\mu_k}_{i_k},$$
(2)

where $\{s_i^{\mu}\}_{\mu,i}$ are operator bases at the site *i*; for example, when we consider a (1/2)-spin system, $\{s_i^{\mu}\}_{\mu,i} = \{\sigma_i^x, \sigma_i^y, \sigma_i^z\}$ with $\{\sigma_i^{\mu}\}_{\mu=x,y,z}$ the Pauli matrices.

C. Definition of extensiveness

We next define the extensiveness as follows: the k-local operator $O^{(k)}$ satisfies the extensiveness if

$$\max_{i \in [1,n]} \left(\sum_{Z: Z \ni i} \| o_Z \| \right) \le g,\tag{3}$$

where g is a $\mathcal{O}(1)$ constant and $\sum_{Z:Z \ni i}$ denotes the summation with respect to the support Z which contains the spin *i*. Note that if the operator $O^{(k)}$ satisfies the extensiveness, it also satisfies

$$\|O^{(k)}\| \le gn,\tag{4}$$

because of

$$||O^{(k)}|| \le \sum_{Z} ||o_{Z}|| \le \sum_{i=1}^{n} \sum_{Z:Z \ni i} ||o_{Z}|| \le gn.$$

D. Definition of the Hamiltonian

In the following, we consider Hamiltonians which are extensive k-local operators with $k = \mathcal{O}(1)$:

$$H = \sum_{|Z| \le k} h_Z \quad \text{with} \quad \sum_{Z:Z \ni i} ||h_Z||_2 \le g \quad \text{for} \quad i = 1, 2, \dots, n,$$
(5)

We also define the finite-range interaction as follows;

$$\sum_{Z:Z \ni \{i,j\}} \|h_Z\| = 0, \quad \text{for} \quad d_{i,j} > \ell_H,$$
(6)

where ℓ_H corresponds to the interaction length.

II. LIEB-ROBINSON BOUND

In this section, we show the Lieb-Robinson bound and its proof in the case of the finite-range interacting systems; even if we consider more general systems (e.g. with exponentially decaying interactions), the Lieb-Robinson bound can be also obtained and its proof is essentially the same as in this case.

The Lieb-Robinson bound restricts the velocity of the information transfer in the time evolution of quantum manybody systems. In other words, if we send some information from a subsystem X to a subsystem Y by the use of the time-evolution of a local Hamiltonian, we need finite time which is proportional to the distance between X and Y.

<u>Lieb-Robinson bound.</u> Let O_X and O_Y be arbitrary operators on the subsystems X and Y, respectively. We then bound the norm of the commutator $[O_X(t), O_Y]$ from above by

$$\|[O_X(t), O_Y]\| \le \frac{2}{k} \|O_X\| \cdot \|O_Y\| \cdot |X| \frac{(2kg|t|)^{m_0}}{m_0!},\tag{7}$$

with

$$m_0 = \left\lfloor \frac{d_{X,Y}}{\ell_H} + 1 \right\rfloor,\tag{8}$$

where $O_X(t) \equiv e^{-iHt}O_X e^{iHt}$ and the Hamiltonian (5) is finite-range as in Eq. (6). The RHS of the inequality is roughly given by

$$\frac{(C|t|)^{m_0}}{m_0!} \sim \left(\frac{\text{const.} \times |t|}{m_0}\right)^{m_0} \sim e^{-\text{const.} \times d_{X,Y} \log(d_{X,Y}/|t|)},\tag{9}$$

which implies the super-exponential decay with respect to the distance $d_{X,Y}$.

Proof. We first prove the following inequality:

$$\frac{a}{lt} \|[O_X(t), O_Y]\| \le 2 \|O_X\| \cdot \|[H_X(t), O_Y]\|.$$
(10)

In order to prove this inequality, we start with the following equation:

$$\|[O_X(t+\delta t), O_Y]\| = \|[e^{-iH(t+\delta t)}O_X e^{iH(t+\delta t)}, O_Y]\|$$

= $\|[e^{-iHt}e^{-iH\delta t}O_X e^{iH\delta t}e^{iHt}, O_Y]\|$
= $\|[(O_X - i\delta t[H, O_X] + \mathcal{O}(\delta t^2), O_Y(-t)]\|$
= $\|[(O_X - i\delta t[H_X, O_X] + \mathcal{O}(\delta t^2), O_Y(-t)]\|,$ (11)

where we define H_X as

$$H_X = \sum_{Z_1:Z_1 \cap X \neq \emptyset} h_{Z_1}.$$
(12)

We then obtain

$$\begin{aligned} \|[e^{-iH_X\delta t}O_X e^{iH_X\delta t}, O_Y(-t)]\| + \mathcal{O}(\delta t^2) &= \|[O_X, e^{iH_X\delta t}O_Y(-t)e^{-iH_X\delta t}]\| + \mathcal{O}(\delta t^2) \\ &= \|[O_X, O_Y(-t) + i\delta t[H_X, O_Y(-t)]\| + \mathcal{O}(\delta t^2) \\ &= \|[O_X(t), O_Y]\| + i\delta t[O_X, [H_X, O_Y(-t)]\| + \mathcal{O}(\delta t^2) \\ &\leq \|[O_X(t), O_Y]\| + 2\delta t\|O_X\| \cdot \|[H_X(t), O_Y]\| + \mathcal{O}(\delta t^2). \end{aligned}$$
(13)

From (11) and (13), we prove the inequality (10) by taking $\delta t \to 0$.

By integrating the inequality (10) and utilizing the fact of $||[O_X(t=0), O_Y]|| = ||[O_X, O_Y]|| = 0$, we obtain the following inequality:

$$\|[O_X(t), O_Y]\| \le 2 \|O_X\| \sum_{Z_1: Z_1 \cap X \neq \emptyset} \left(\|[h_{Z_1}(0), O_Y]\| + \int_0^t \|[h_{Z_1}(t_1), O_Y]\| dt_1 \right)$$
$$= 2 \|O_X\| \sum_{Z_1: Z_1 \cap X \neq \emptyset} \int_0^t \|[h_{Z_1}(t_1), O_Y]\| dt_1,$$
(14)

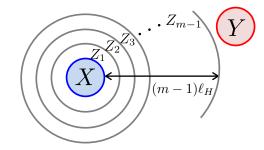


FIG. 1: The regions $\{Z_j\}_{j=1}^m$ in the inequality (16) is defined as $Z_j : Z_j \cap Z_{j-1} \neq \emptyset$. Because the interactions in the Hamiltonian are short-range with interaction length ℓ_H , for each of the terms h_{Z_j} , the subset Z_j satisfies $d_{X,i} < j\ell_H$ for an arbitrary site $i \in Z_j$.

where we use $\|[h_{Z_1}(0), O_Y]\| = 0$ as long as $Z_1 \cap Y = \emptyset$. Because we assume the finite-range interaction, we here note that arbitrary site *i* in the set $Z_1 : Z_1 \cap X$ satisfies $d_{i,X} < \ell_H$ for $\forall i \in Z_1$ (Figure 1). If all the commutators $\|[h_{Z_1}, O_Y]\|$ vanish, namely $d_{X,Y} > \ell_H$ we apply the same process to $\|[h_{Z_1}(t), O_Y]\|$ and obtain

$$\|[O_X(t), O_Y]\| \le 4 \|O_X\| \sum_{Z_1: Z_1 \cap X \neq \emptyset} \|h_{Z_1}\| \sum_{Z_2: Z_2 \cap Z_1 \neq \emptyset} \int_0^t \int_0^{t_1} \|[h_{Z_2}(t), O_Y]\| dt_2 dt_1$$
(15)

as long as $Z_1 \cap Y = \emptyset$. Note that arbitrary site *i* in the set Z_2 satisfies $d_{i,X} < 2\ell_H$.

By iteratively applying this process, we have

$$\begin{split} \|[O_{X}(t), O_{Y}]\| &\leq 2^{m} \|O_{X}\| \sum_{Z_{1}:Z_{1}\cap O_{X}\neq\emptyset} \|h_{Z_{1}}\| \sum_{Z_{2}:Z_{2}\cap Z_{1}\neq\emptyset} \|h_{Z_{2}}\| \cdots \sum_{Z_{m-1}:Z_{m-1}\cap Z_{m-2}\neq\emptyset} \|h_{Z_{m-1}}\| \\ &\sum_{Z_{m}:Z_{m}\cap Z_{m-1}\neq\emptyset} \int_{0}^{t} \int_{0}^{t_{1}} \cdots \int_{0}^{t_{m-1}} \|[h_{Z_{m}}(t_{m}), O_{Y}]\| dt_{m} dt_{m-1} \cdots dt_{1}. \\ &\leq 2^{m} \|O_{X}\| \sum_{Z_{1}:Z_{1}\cap O_{X}\neq\emptyset} \|h_{Z_{1}}\| \sum_{Z_{2}:Z_{2}\cap Z_{1}\neq\emptyset} \|h_{Z_{2}}\| \cdots \sum_{Z_{m-1}:Z_{m-1}\cap Z_{m-2}\neq\emptyset} \|h_{Z_{m-1}}\| \\ &\sum_{Z_{m}:Z_{m}\cap Z_{m-1}\neq\emptyset} \int_{0}^{t} \int_{0}^{t_{1}} \cdots \int_{0}^{t_{m-1}} 2\|h_{Z_{m}}\| \cdot \|O_{Y}\| dt_{m} dt_{m-1} \cdots dt_{1} \end{split}$$
(16)

under the assumption that all the commutators $||[h_{Z_{m-1}}, O_Y]||$ vanish. From $d_{X,i} < (m-1)\ell_H$ for an arbitrary site $i \in Z_{m-1}$, as long as $d_{X,Y} \ge (m-1)\ell_H$, we can ensure $[h_{Z_{m-1}}, O_Y] = 0$. Therefore, the condition $[h_{Z_{m-1}}, O_Y] = 0$ is ensured up to $m = m_{\max}$ with

$$m_{\max} = \left\lfloor \frac{d_{X,Y}}{\ell_H} + 1 \right\rfloor. \tag{17}$$

Because of the extensiveness (5) of the Hamiltonian, we obtain

$$\sum_{Z_1:Z_1\cap X\neq\emptyset} \|h_{Z_1}\| \le \sum_{i:i\in X} \sum_{Z_1:Z_1\ni i} \|h_{Z_1}\| \le \sum_{i:i\in X} g = g|X|.$$
(18)

Similarly, we have

$$\sum_{Z_1:Z_1\cap Z_2\neq\emptyset} \|h_{Z_2}\| \le \sum_{i:i\in Z_1} \sum_{Z_2:Z_2\ni i} \|h_{Z_2}\| \le \sum_{i:i\in Z_1} g = g|Z_1| \le kg,\tag{19}$$

where we utilize k-locality of the Hamiltonian as in Eq. (5).

By the use of the inequalities (18) and (19) in (16), we obtain

$$\|[O_X(t), O_Y]\| \le 2^{m+1} \|O_X\| \cdot \|O_Y\| \cdot |X| k^{m-1} g^m \int_0^t \int_0^{t_1} \cdots \int_0^{t_{m-1}} dt_m dt_{m-1} \cdots dt_1$$
$$= \frac{2}{k} \|O_X\| \cdot \|O_Y\| \cdot |X| \frac{(2kgt)^m}{m!}.$$
(20)

By taking m as $m_{\text{max}} =: m_0$, we can obtain the main inequality. \Box